Meeting Minutes: 11/14/16

Attendance: all

Location: ARC108

What has changed since last meeting:

* Group
  + Met with Dr. Zhu and Miguel to begin preperation for the eecs retreat/discuss the state of the RoboCat
* Q
  + Further cat head movement debugging. Improved performance.
* Seattle
  + Stored accelerometer data, print on onPause() calls of main intent
* Luke
  + Debugged tracking in video feed so that it no longer crashes

**Immediate goals:**

1. Voice Recognition Team
   1. Alex -
      1. Debug active listening
      2. Remove openCV
   2. Kurtis -
      1. Make cat response to yes and no
      2. Begin emotion detection
2. Environmental Mapping
   1. Zach:
      1. Get data from ultrasonic sensor to the arduino then the phone
   2. Seattle
      1. Finish accelerometer output to txt file
      2. Revise system architecture diagram
3. Facial Recognition/color Tracking
   1. Quintin:
      1. Increase accuracy of head movement
      2. Use smile values to affect the emotion of the cat
   2. Lukas:
      1. Modify color tracking to work with video feed
      2. Compile standalone into main app